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#### Lecture 6

# The complexity of

$$\mathfrak{A}\models\phi$$

FOL

SOL

 $\exists SOL$ 

HornSOL

# Computing $\mathcal{M}(\mathfrak{A},z,\phi)$ , I

#### Given

 $\mathfrak{A}$ , a  $\tau$ -structure with |A| = m

 $\phi \in FOL(\tau)$  of length n and quantifier depth q

z an assignment  $z: Var_{FOL} \rightarrow A$ 

We want to compute **inductively** the meaning function

$$\mathcal{M}(\mathfrak{A},z,\phi)$$

and estimate its computational complexity with respect to time and space denoted by

$$TIME(\mathfrak{A}, z, \phi), SPACE(\mathfrak{A}, z, \phi)$$

# Computing $\mathcal{M}(\mathfrak{A},z,\phi)$ , II

Recall that  $\tau$  is purely relational and terms t are either constants or variables.

#### Atomic formulas:

$$R(t_1, t_2, \ldots, t_r)$$
 with  $R \in \tau$  and  $t_1 \approx t_2$ .

Takes one step in a random access look-up table.

Takes  $m^r$ , resp.  $m^2$  steps for searching the table.

One bit space for the result.

#### Boolean operations:

$$\phi = (\phi_1 \land \phi_2), \ \phi = (\phi_1 \lor \phi_2), \ \phi = \neg \phi_1$$

$$TIME(\mathfrak{A}, z, \phi) = TIME(\mathfrak{A}, z, \phi_1) + TIME(\mathfrak{A}, z, \phi_2) + 1$$

$$SPACE(\mathfrak{A}, z, \phi) = max(SPACE(\mathfrak{A}, z, \phi_1), SPACE(\mathfrak{A}, z, \phi_2))$$

## Computing $\mathcal{M}(\mathfrak{A},z,\phi)$ , III

#### Quantifiers:

$$\phi = \exists x \phi_1(x), \ \phi = \forall x \phi_1(x)$$

We search the structure for an element, hence  $TIME(\mathfrak{A}, z, \phi) = m \cdot TIME(\mathfrak{A}, z, \phi_1)$ 

We can denote location of search in binary, hence  $SPACE(\mathfrak{A}, z, \phi) = \log m \cdot SPACE(\mathfrak{A}, z, \phi_1)$ 

#### Conclusion:

$$TIME(\mathfrak{A}, z, \phi) = O(n \cdot m^q)$$

$$SPACE(\mathfrak{A}, z, \phi) = O(q \cdot \log m)$$

# Computing $\mathcal{M}(\mathfrak{A},z,\phi)$ , IV

We have considered two problems for FOL:

1. The combined complexity of  $\mathcal{M}(\mathfrak{A},z,\phi)$  where both  $\mathfrak{A}$  and  $\phi$  are the input.

This is in PSPACE.

2. The complexity of  $\mathcal{M}(\mathfrak{A},z,\phi)$  for fixed  $\phi$ , where only  $\mathfrak{A}$  is the input.

This is in  $\mathbf{P}$  and even in  $LOGSPACE \subseteq \mathbf{P}$ .

# Computing $\mathcal{M}(\mathfrak{A},z,\phi)$ , V

Now we consider SOL.

The only change comes from the quantifiers: Search is over all subsets of  $A^r$ .

This takes time  $2^{m^r}$ .

The characteristic function of these sets has size  $m^r$ .

#### Conclusion:

$$TIME(\mathfrak{A}, z, \phi) = O(n \cdot 2^{q \cdot m^r})$$

$$SPACE(\mathfrak{A}, z, \phi) = O(q \cdot \log m^r) = O(q \cdot r \cdot m)$$

# Computing $\mathcal{M}(\mathfrak{A},z,\phi)$ , VI

We consider two problems for SOL:

1. The combined complexity of  $\mathcal{M}(\mathfrak{A},z,\phi)$  where both  $\mathfrak{A}$  and  $\phi$  are the input.

This is also in PSPACE.

2. The complexity of  $\mathcal{M}(\mathfrak{A},z,\phi)$  for fixed  $\phi$ , where only  $\mathfrak{A}$  is the input.

This is in PSPACE.

# Computing $\mathcal{M}(\mathfrak{A},z,\phi)$ , VII

We want to use now non-deterministic machines.

We denote by  $\exists SOL(\tau)$  the set of  $SOL(\tau)$ -formulas  $\psi$  of the form

$$\psi = \exists X_1 \exists X_2 \dots \exists X_k \phi(X_1, X_2, \dots, X_k)$$
 with  $\phi \in FOL(\tau \cup \{X_1, X_2, \dots, X_k\})$ 

For fixed  $\psi \in \exists SOL$  we have that  $\mathcal{M}(\mathfrak{A}, z, \psi)$  is in **NP**.

Hence, for fixed  $\psi \in SOL$  we have that  $\mathcal{M}(\mathfrak{A}, z, \psi)$  is in PH, the **Polynomial Hierarchy**.

## The Polynomial Hierarchy, I

We look at **Oracle Turing Machines** OTM. Let X be a problem and C be a class of problems.

#### We define

 $\mathbf{P}^X = \{Y : \exists M \text{ accepts } Y \text{ using } X \text{ as oracle } \}$   $\mathbf{P}^C = \{Y : \exists M \text{ accepts } Y \text{ using } X \in C \text{ as oracle } \}$ Here M is a deterministic polynomial time OTM.

#### Similarly,

 $\mathbf{NP}^X = \{Y : \exists M \text{ accepts } Y \text{ using } X \text{ as oracle } \}$   $\mathbf{NP}^C = \{Y : \exists M \text{ accepts } Y \text{ using } X \in C \text{ as oracle } \}$ Here M is a non-deterministic polynomial time OTM.

## The Polynomial Hierarchy, II

We define inductively:

$$\Delta_0 P = \Sigma_0 P = \Pi_0 P = P$$

and

$$\Delta_{i+1}P = P^{\Sigma_i}P$$
  

$$\Sigma_{i+1}P = NP^{\Sigma_i}P$$
  

$$\Pi_{i+1}P = CoNP^{\Sigma_i}P$$

Finally,

$$PH = \bigcup_{i \in \mathbb{N}} \Sigma_i P$$

Note that  $PH \subseteq PSPACE$  and P = NP iff P = PH.

## Horn formulas, I

A **propositional Horn clause** is a formula of the form

$$\neg p_1 \lor \neg p_2 \lor \ldots \lor \neg p_m \lor q$$

with atmost one variable unnegated.

Equivalently, we can write

$$(p_1 \wedge p_2 \wedge \ldots \wedge p_m \rightarrow q)$$

m= 0 gives  ${f true} 
ightarrow q$  and the absence of q gives

$$(p_1 \wedge p_2 \wedge \ldots \wedge p_m \to \text{false})$$

or

$$\neg (p_1 \land p_2 \land \ldots \land p_m)$$

A FOL Horn clause is obtained by replacing variables by atomic formulas.

## Horn formulas, II

The size s(C) of a clause C is the number of variables occurring in  $\Sigma$ .

The size  $s(\Sigma)$  of set of clauses  $\Sigma$  is defined as  $\sum_{C \in \Sigma} s(C)$ 

SAT is the problem of deciding whether a set  $\Sigma$  of clauses with n variables of size m is satisfiable.

**Theorem:** SAT can be solved in  $TIME(2^n \cdot m)$  and is **NP**-complete.

HORNSAT is like SAT but with  $\Sigma$  a set of Horn clauses.

**Theorem:** HORNSAT is in **P**.

**Proof:** Use unit resolution.

## Horn formulas, III

The formulas of  $Horn \exists SOL$  are of the form

$$\Psi = \exists X_1 \exists X_2 \dots \exists X_j \forall x_1 \forall x_2 \dots \forall x_k \bigwedge_{\ell=1}^n \Phi_\ell$$

where each  $\Phi_{ell}$  is a FOL-Horn clause.

#### Theorem:(Grädel)

For  $\Psi$  a fixed  $Horn\exists SOL$  formula  $\mathcal{M}(\mathfrak{A},z,\phi)$  is in  $\mathbf{P}$ .

We give a proof.

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#### Horn formulas, IV

For simplicity let

$$\Psi = \exists X \forall x_1 \forall x_2 \dots \forall x_k \bigwedge_{\ell=1}^n \Phi_\ell$$

a  $au_{graphs}$ -formula with X r-ary.

So each  $\Phi_{\ell}$  consists of atomic or negated atomic formulas  $x_i \approx x_j$ ,  $E(x_i, x_j)$  or  $X(x_{i_1}, \dots, x_{i_r})$ .

Let  $\mathfrak{A}$  be a structure with elements  $a_1, \ldots, a_n$ .

There are  $n_k$  many assignments for the variables  $x_i$ .

Let h be the length of  $\Phi = \bigwedge_{\ell} \Phi_{\ell}$ .

## Horn formulas, V

We now form the formula

$$\bigwedge_z subst(\Phi, z)$$

This formula has exactly  $h \cdot n^k$  many literals.

In  $\mathfrak{A}$  each atomic formula  $E(a_i, a_j)$  or  $a_i \approx a_j$  is true or false, so we can replace them by true or false respectively.

We replace each  $X(a_{i_1},\ldots,a_{i_r})$  by a propositional variable  $p_{a_{i_1},\ldots,a_{i_r}}$ .

We obtain so a propositional formula  $\bar{\Psi}$ .

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## Horn formulas, VI

#### Claim 1:

If  $\mathfrak{A}\models\Psi$  then  $\bar{\Psi}$  is satisfiable.

**Proof:** Assume  $\mathfrak{A} \models \Psi$ .

Then there is  $U \subset A^r$  such that

$$\mathfrak{A}, U \models \forall x_1 \forall x_2 \dots \forall x_k \bigwedge_{\ell=1}^n \Phi_\ell$$

.

We now define an assignement

$$z(p_{\overline{a}}) = \begin{cases} 1 & \text{if } \overline{a} \in U \\ 0 & \text{if } \overline{a} \notin U \end{cases}$$

**Exercise:** Show that this z makes  $\overline{\Psi}$  true.

## Horn formulas, VII

#### Claim 2:

If  $\overline{\Psi}$  is satisfiable then  $\mathfrak{A} \models \Psi$ .

**Proof:** Assume z is an assignement which makes  $\bar{\Psi}$  true.

We define an interpretation U for X by

$$\bar{a} \in U \text{ iff } z(p_{\bar{a}}) = 1$$

.

Exercise: Show that

$$\mathfrak{A}, U \models \forall x_1 \forall x_2 \dots \forall x_k \bigwedge_{\ell=1}^n \Phi_\ell$$

.

## Horn formulas, VII

#### **Proof of Theorem:**

- $\bullet$  The construction of  $\overline{\Psi}$  from  $\Psi$  is done in polynomial time
- $\bullet$  The size of  $\overline{\Psi}$  is polynomial in the size of  $\Psi.$
- $\bullet$  Using the polynomial time algorithm for HORNSAT, we check the satisfiability of  $\bar{\Psi}.$
- Using the lemma, this settles  $\mathfrak{A} \models \Psi$ .

#### 2SAT

Let  $\Sigma$  be a set of propositional clauses of at most two literals each.

These are sometimes called Krom clauses.

Both Horn and Krom are names of Logicians

2SAT is the problem of deciding whether such a  $\Sigma$  is satisfiable.

NL denotes the class of problems decidable in non-deterministic logarithmic space.

**Theorem:** 2SAT is decidable in NL.

 $Krom \exists SOL$  is like  $Horn \exists SOL$  but with clauses of size 2 rather than Horn cluases.

It is now easy to prove that

**Theorem:** For fixed  $\Psi \in Krom \exists SOL$  the problem  $\mathcal{M}(\mathfrak{A}, z\Psi)$  is in  $\mathbf{NL}$ .

The proof is exactly like for  $Horn \exists SOL$ .

# Definability and Complexity, I

Let K be a class of finite  $\tau$ -structures.

Let  $\mathcal{L}(\tau) \subseteq SOL(\tau)$ .

Typically  $\mathcal{L}(\tau)$  is one of  $Krom\exists SOL(\tau),\ Horn\exists SOL(\tau),\ SOL(\tau),\ MSOL(\tau),$ 

K is **definable in**  $\mathcal{L}(\tau)$  if there exists  $\Psi \in \mathcal{L}(\tau)$  such that

$$\mathfrak{A} \in K \text{ iff } \mathfrak{A} \models \Psi$$

Let C be a complexity class. typically LOGSPACE, NL, P, NP, PH, PSPACE

K is in  $\mathbb{C}$  iff the problem  $\mathfrak{A} \in K$  can be decided with the resources allowed in  $\mathbb{C}$ .

## Definability and Complexity, II

#### We have shown:

- If K is definable in FOL then  $K \in LOGSPACE$ .
- If K is definable in  $Krom \exists SOL$  then  $K \in \mathbf{NL}$ .
- If K is definable in  $Horn\exists SOL$  then  $K \in \mathbf{P}$ .
- If K is definable in  $\exists SOL$  then  $K \in \mathbf{NP}$ .
- If K is definable in SOL then  $K \in \mathbf{PH}$ .

## Definability and Complexity, III

# We will show in the sequel for **ordered structures**

- (Grädel) If  $K \in \mathbf{NL}$ , then K is definable in  $Krom \exists SOL$ .
- (Grädel) If  $K \in \mathbf{P}$ , then K is definable in  $Horn \exists SOL$ .

#### For arbitrary structures we have

- (Fagin, Christen) If  $K \in \mathbf{NP}$ , then K is definable in  $\exists SOL$ .
- (Meyer and Stockmeyer) If  $K \in \mathbf{PH}$ , then K is definable in SOL.

#### LOGSPACE

What about FOL-definability and LOGSPSACE?

#### **Exercise:**

Show that the set of words of even size is not FOL-definable.

#### **Exercise:**

Show that the set of words of even size is in LOGSPACE.

#### **Exercise:**

Conclude that FOL-definability is weaker than decidability in LOGSPACE.

#### **Questions:**

Which logic corresponds to LOGSPACE? FOL+determinsitic transitive closure

Which complexity class corresponds to FOL? The circuit complexity class  $AC_0$ .